CCD Imaging and Processing - AA3

A Tutorial by Alan Chen

Member of: CFAS: Central Florida Astronomical Society Chiefland Astronomy Club

CCD Imaging and Processing

- The camera
- Matching scope with camera
- Taking the image
- Processing the image
- Final results

 Choosing the camera Many different options to start imaging with Digital camera - easiest way to start Research the web for choices Nice results achieved with Olympus, Nikon and others SLR's coming into popularity (like the Canon D6O) but expensive Webcam - excellent for planets (check QCUIAG) True CCD version (not CMOS based) » Philips Toucam Pro, Vesta Pro, Older Logitech/Connectix Video camera - I.e. StellaCam-EX: deepsky capable True CCD camera for astro-imaging

• True CCD camera

- Several major CCD camera vendors
 - Apogee high end cameras (i.e. more expensive)
 Utilizes SITE chips very sensitive as a result of back illumination
 - FLI high end cameras (i.e. more expensive)
 Also utilizes back illuminated chips, but has more inexpensive offerings as well from Kodak
 - SAC very inexpensive to start with
 SAC8 the best choice, but requires parallel and USB ports
 Older models use vid cam technology for summed exposures
 Lacks strong software support, but still relatively new

• True CCD camera Several major CCD camera vendors SBIG - probably the largest and most recognizable Wide range of cameras based on Kodak chips Excellent standalone autoguiders (STV, ST4) Starlight Express - great values in a true ccd camera Wide range of cameras based on Sony chips All are good choices and span prices ranges for all levels of imager

 Starlight Express - my choice in 2001! MX7C - why was this a good choice for me? An excellent first camera Good for starters and advanced imagers Relatively simple to operate, especially for color images Affordable by CCD standards 750x582 resolution tops in its price range Small and compact - 2" dia Light weight Balance kit not necessary for the LX200 Approximately the weight of a good 2" eyepiece Primary SBIG equivalent considered: ST-7E

• Starlight Express MX7C - why was this a good choice for me? One shot camera - color matrix filters - CMY Synthesizes RGB from the filtered signals Much less overall imaging time involved for color » Color filter wheel not required Probably not as accurate a color balance as RGB imaging Color synthesis routines much improved recently in Astroart Self-guiding capability with Star2000 interface Uses the same chip for imaging and guiding Sensitivity reduced by 50% as a result Full frame can be used to locate a suitable guidestar! Simple software interface to self-guide

Starlight Express

- Today's alternate choices I would consider
 - MX716 very sensitive and low cost the best value on the market today
 - SXV-H9 very sensitive megapixel camera Extremely low noise/dark current Dark frame not used by many SXV imagers
 - SXV-H9C good sensitivity, especially for color
 Uses an RGBG (Bayer Matrix) not CMYG
 - Color resolution will be much improved
 - Extremely low noise/dark current
 - Primary SBIG equivalent to consider: ST2000XM

Matching Scope and Camera

- General guidelines
 - Sampling depends on seeing
 - Good seeing (i.e. <2 arc-sec) can tolerate higher resolution sampling rates
 - Sampling rate (arc-sec/pixel) = 206 x (pixel size)/(focal length)
 - » Pixel size is dependent on the camera
 - » FL can be varied by focal reducers and barlow lenses Scope and camera should provide a typical sampling rate of between 1 and 3 arc-sec/pixel
 - » 12"LX200 @ f/3.3 = 1.7 arc-sec/pixel (good match!)
 - » Rates>2 is undersampling and rates<2 is oversampling
 - » High resolution imagers use 1/3 to 1/4 the seeing value to maximize resolution (i.e. down to 0.5 arc-sec/pixel!)

- Imaging process
 - Setup the optics/camera
 - The all-threaded setup is preferred and offers flexibility



Complete rigid coupling (all threaded)



Complete setup with visual back (not as rigid as threaded setup)

- Imaging process
 - Setup scope, camera, laptop and align
 - No hot plugging turn everything on after full setup



Imaging process Choose and locate first object For LX200, slew to it using HPP (nice ccd feature) HPP targets a nearby bright star to center Use this opportunity to focus CCD camera on star Finally slew to object For other setups, manually locate or goto Focus on a nearby star when convenient Note: Astroart is referenced in this presentation Great support for all Starlight cameras and others makes Relatively inexpensive (~\$150) - version 3 is current » Handles both camera control and image processing

Taking the Image

Take a quick 5 to 30 second image of the object

	М	ISB Astroart 2.0	
	File	Edit View Image Filters Arithmetic Iools Window Help	
	i ≥	#11 NoName10.fit	
• •			
	6		
		MX7C USB Camera - Control panel	
8		Image Sequence Dark/Flat Focus/Guide Settings Setup	
	C	Automatic visualization	
	•	Custom visualization	
	Ø	200 € 20000 € -5 € Check CCD	
•	THE		
	œ		
	130	START 5	
	+7	ОК	
	m		
	E F		
	0		
	Θ,		

Taking the Image

Select a star anywhere on the image to fine focus



Taking the Image

Select the focus box - star is rough focused



 Depending on the star's brightness, vary the exposure to generate a reasonable signal level (Peak=xxx)

 Adjust the focuser to maximize the Peak value and minimize the FWHM values for both x and y directions

Good focus has been achieved



 Peak has increased from 406 to 914 and the FWHM values have dropped to 1.1 and 1.2 pixels

 Note also the 'look' of the star in the focus window - only a single pixel is essentially used

 Autoguider setup Separate guide scope with Mintron 12V1 low lux vidcam Star2000 equally effective with similar setup process Scope setup under "Telescope Control" Correction speed (pixel/sec) Correction range ("Ignore") Backlash (set to zero if setup) on the scope)



Taking the Image

Set the exposure time (240s in this case)

The late law proper likes defined. Then whithe data	Mark quide star RE Tolescope Close	
The law proof that second for some the second for an and the second for an and the second for a	✓ Mark guide star P(Totescope Char Ø 1 A	• gu be (o dy
	Stolight/Vpmm Relay box, ST4 mode CDM 1 Telescope speed Finel/tec) Tproze × 75 g F Revenue Out + 10 g Y 75 g P Revenue Out + 10 g Datases Det backlash Fange XY F Adamte pade Paus star pade 12 g	• be ar
NOT IDE Carrier Control activit	Convert Disconnect VI	SC
Dakhare Shervedan Texturbate Setup: 1 = 1 = 1 = 1 = 1 = 1 = 1 = 1 = 1 = 1	Inage Seguence Dak/Flat Facus/Sude Settings Setup C Dak None C Take verdare Take verdar C Telescope	th
FIT's date. Object: Chernely	FITS data Object, Conner#	W
STOP 240 - 35	STARE 3.0 . K. K	m
Start Advant Diversion Diversion	Telescope Cartal	

Note the good iding errors ing reported x = -0.1 and = 0.2 pixels) f the FL ratio tween main nd guide copes is 2:1, en the error I be 2x on the ain scope

 To take the image, select the image or sequence tab Image generates a single image (i.e. 300 sec here) Sequence allows multiple images to be taken and saved (i.e. 5 images of M101)



Processing the image

Astroart has it own internal color synthesis
 routing

 It also allows use of external plugins This presentation will focus on the use of Astroart ver3 (AA3) in conjunction with a plugin developed by **Mike Smith**



 Go to the Synthesis tab and turn the Luminance HPF to off (you can adjust sharpness on your own later)



 Proceed to the Color Adjust tab I have found a reasonable starting point to use RGB ratios of 0.45:0.95:1.00 Adjust the altitude for the object



フフ

 The preview window will show the results after each update The colors should be close, but can be tweaked by RGB ratios • The Luminance slider was raised to show the colors better



Processing the image

Batch processing: selecting the images



Batch processing: results in LRGB separation Process dark files at the same time

Folders	×	Name	Size	Туре	Date Modified -
🗐 🦳 Data Files	-	8_m16ac004.fit	855 KB	CCD Image	6/29/2003 2:20 PM
Smin dark for 10 5 02		G_m16ac004.fit	855 KB	CCD Image	6/29/2003 2:20 PM
Barbara H		L_m16ac005.fit	855 KB	CCD Image	6/29/2003 2:20 PM
E CEAS star party 2002		R_m16ac005.fit	855 KB	CCD Image	6/29/2003 2:20 PM
t Chiefland 4 6 03		8_m16ac005.fit	855 KB	CCD Image	6/29/2003 2:21 PM
Chiefland m98 m16 ir5146.0	062	G_m16ac005.fit	855 KB	CCD Image	6/29/2003 2:21 PM
ir5146 recoop		L_m16ac006.ft	855 KB	CCD Image	6/29/2003 2:21 PM
D m16		B_m16ac006.fit	855 KB	CCD Image	6/29/2003 2:21 PM
in man		G_m16ac006.fit	855 KB	CCD Image	6/29/2003 2:21 PM
0006888		R_m16ac006.fit	855 KB	CCD Image	6/29/2003 2:21 PM
Chris (denturist)		L_m16ac007.Fit	855 KB	CCD Image	6/29/2003 2:21 PM
Dave C		B_m16ac007.fit	855 KB	CCD Image	6/29/2003 2:21 PM
Deep		G_m16ac007.fit	855 KB	CCD Image	6/29/2003 2:21 PM
Dadi		R_m16ac007.fit	855 KB	CCD Image	6/29/2003 2:21 PM
Ereds folder		L_m16ac008.fit	855 KB	CCD Image	6/29/2003 2:21 PM
F C Home 1 9 03		8_m16ac008.fit	855 KB	CCD Image	6/29/2003 2:21 PM
E borne 1 18 03		G_m16ac008.fit	855 KB	CCD Image	6/29/2003 2:21 PM
boxe 1 19 03		R_m16ac008.fit	855 KB	CCD Image	6/29/2003 2:21 PM
E borne 2 15 03		8_m16ac009.fit	855 KB	CCD Image	6/29/2003 2:21 PM
+ bone 2 21 03		G_m16ac009.fit	855 KB	CCD Image	6/29/2003 2:21 PM
E home 3 28 03		L_m16ac009.ft	855 KB	CCD Image	6/29/2003 2:21 PM
Dimage drift studies		R_m16ac009.fit	855 KB	CCD Image	6/29/2003 2:21 PM
C lapet		B_Dark04.fit	855 KB	CCD Image	6/29/2003 2:21 PM
in Jeffs folder		G_DarkO4.fit	855 KB	CCD Image	6/29/2003 2:22 PM
D spter		R_Dark04.fit	855 KB	CCD Image	6/29/2003 2:22 PM
mi at f6 losmandy mount 1	22	L_Dark04.fit	855 KB	CCD Image	6/29/2003 2:26 PM
and the second state and and a					(0) (0) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1

• Pre-processing: selecting stars to autoalign Pull up the first luminance frame in the sequence Select 2 stars on opposite sides of the frame (a "+" will show on the star)



Processing the image

Pull up the Pre-processing window - choose Auto alignment

Select "Two stars" - ideal to remove image rotation

· · · ·	•
	C

Flat Fields C Median (# Average	Dark Frames C Median	F.D. Frames C Median (* Average	Bies C Median (* Average	F. Bias C Median (F Average	Method C One star	(€ Two	itari (° Co	relation	C Plane
Images C Add	(* Average	С Кеер	Operations (* Enabled	C Disabled	Stars X1, Y1, R1 =	137	2 73	٢	40
Options					X2, Y2, R2 =	472	372	÷	40
Confirm each Keep each im	mage age	Auto alignment	☐ Save ☐ M0< co	each image ilor synthesis	√ 0K		Cancel		

Processing the image

The default range is 20 - increase this to 40 if there's substantial movement of the stars from frame to frame (drift)

	· · ·	
	0	181 - E
• •	active at	

Flat Fields C Median (* Average	Dark Frames C Median R Average	F.D. Frames C Median (* Average	Biss C Median (* Average	F. Bias C Median G Average	Method C One star	I Two st	tars (° Co	relation	C Plane
Images C Add	(F Average	С Кеер	Operations (* Enabled	C Disabled	Stars X1, Y1, R1 =	137	273	•	40
Options					X2, Y2, R2 =	472	372	•	40
Confirm each	h image mage	Auto alignment	T Save	each image Ior synthesis	J 0K		Carcel		

Processing the image

• Pre-processing: select files to combine

Include darks (in this case for luminance frames)

• The larger the number of darks, the better (the noise on dark frames behaves the same way as on light frames) • L_DarkO4 is an average of 6 darks

A 199 A 19 A 19 A 199 A 199				, P. Diali	
TTS Sker	•	Images L_m15ac001.00 L_m15ac002.00	Dath Flames	Bier	_
B_w16.9t B_w16ac001.7t B_w16ac002.7t B_w16ac002.7t B_w16ac003.7t	1	L_m16ec003.H L_m16ec003.H L_m16ec005.H L_m16ec005.H L_m16ec005.H L_m16ec007.H L_m16ec008.H			

Pre-processing: 14x4min. images combined



Processing the image

DDP processing - compresses signal range



DDP processing - result of ddp filter



Unsharp Mask filtering - use Adaptive



 Unsharp Mask filtering
 Sharpens the fine nebulosity and tightens the star images

Arithmetic Color Tools Window Help - 🗆 🗙 m16lum.fi R = 4:2584 B = 1660 V = 1469:2223 Lin - 0 🎽 #20 NoName01.fit R = 4:3204 B = 1666 V = 1469:2223 Lin

Stretching the image with a histogram

• Although useful on nebulae images to enhance faint details, log stretching also tends to washout contrast Log stretching was not used on the final M16 pic



Color processing

- Repeat the procedure as in slide 29 to combine all of the R-frames together, then the G-frames and finally the B-frames
 - Again, use the appropriate dark frame and save files
 - Upon completion, there should be one L, R, G and B frame (4 total frames)



Processing the image

 Color processing - Pull up Trichromy from the Color menu

 Ratios are available to adjust if the initial RGB ratios from synthesis requires tweaking

				•	
2 #2	3 G_m16	m			
	•				•
	24	R_m16.fit			
		۰.	Trichromy		
	L	2211 m	Images	1.100.01	RGB/CMY
			AND A CONTRACT OF A DATE		C. DICD
	ſ		8241_m18.18	1.0 -	re nuo
			#23 g_m16.fit	1.0 •	C DMY
			#23 g_m16.fit #22 b_m16.fit	10 10	C DMY

Color processing Selecting OK brings up an RGB image complete with color! A color balance window also pops up Adjust the colors as required to suit



 Color processing Under the Color menu, bring up **LRGB** Synthesis Select the **luminance** frame to combine (L_m16sharp.fit in this example)



Processing the image

Color processing - LRGB combined result



Color processing Use color balance and saturation commands to further enhance the image Flipped image for orientation



Color processing - tweaking in Corel Photopaint



Corel Photo - resampling to square the pixels



Corel Photo - Eliminating image defects



Processing the image

Corel Photo - Using the clone tool Replaces the circled region with nearby attributes

Corel PHOTO-PAINT 8 - new-1.cpl Object Movie Image Effects Mask 월 월 만 한 화 표 🖸 🖬 🖬 🖬 🖬 🖬 🕷 🐐 🖬 🖬 Ba 68 500% Custom Normal * 👼 m 1 6c hiefland. bmp 👼 new-1.cpt (24-Bit RGB Color)-Background D2

Corel Photo - selective Gaussian blur



Corel Photo

- Tweak colors as required
- Save as TIF or with compression as a JPEG



M16 - The Eagle Nebula: final result



chen